

# SDK Builds using Make

**NITRO-SDK**

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## **0 Introduction**

This document describes the features of the makefile in the NITRO-SDK build environment.

- (1) `make command`
- (2) `make target`
  1. `make [build]`
  2. `make clean/clobber`
  3. `make install`
  4. `make run`

## **1 make Command**

The `make` command is a tool that automates procedures (such as compiling applications).

A `make` command, when executed, reads a file described in the compiler procedure (usually the file called `Makefile` in the current directory) and then calls the compiler and linker following the descriptions in that file.

This NITRO-SDK uses GNU make 3.80.

Execute `make` by entering the command as shown below from the Cygwin or Windows command prompt.

```
% make
```

You can set the following options and variables with the `make` command as well as specify target names to change the operation of the `make` command.

```
% make [option] [variable name = set value] [target name]
```

## 2 make Target

In order to simplify the descriptions of the makefile, this SDK provides files, in the directory shown below, that combine descriptions for procedures often used when producing games.

Directory	<code>\$NitroSDK/build/buildtools/</code>
Definition (such as variables) file	<code>commondefs</code>
Compiler procedure definition file	<code>modulerules</code>

Developers creating applications should include and use these two files. Refer to the makefile used to compile a sample class for details on how to include the files.

Targets defined in these files will be described below.

### a. Target Build

- Command    `% make`  
              `% make build`
- Process     Starts the compiler and creates a final target.
- Procedure
  1. Execute the `make build` command for each directory set in `SUBDIRS`.
  2. Create the required work directory.
  3. Compile/assemble the files specified in `SRCS` and then create an object file.
  4. Link the object file to create the file specified in `TARGET_BIN`.
  5. If necessary, install (copy) the files that were created.

Because `build` will become the default target name when you omit the target value of `make`, you can also execute the `make build` process by only typing `make`.

Because the `make` command is called more than once in step 1 of the procedure, you only need to execute the `make` command one time for the first parent directory in the tree to execute the command for all subsequent directories after the parent directory.

The work directory is a directory that will have target devices (TEG, TS) and debug levels (Debug/Release/Rom) of programs currently being compiled, such as `obj/ARM9-TEG/Release`, added to it. You can change the target devices (platforms) and debug levels of these compiler targets by variable settings (described below) and setting values of environment variables as command line options.

```
% make NITRO_DEBUG=TRUE      : Builds target of debug version.
```

Refer to “Environment variables during builds of the SDK” and “Macro Switches Set Within a Makefile of the SDK” on the build switch description page `$NitroSDK/docs/SDKRules/Rule-Defines.html` for details on other variable names and other topics.

A description of the setting variables (`INSTALL_TARGETS / INSTALL_DIR`) for files and directories

specified in the installation procedure in step 5 of the procedure is also included on the build switch description page. Usually, specifying items for the installation procedure is done when specifying libraries in the compiler target and copying created library files to a designated location.

Set the file name in `TARGET_LIB` when you want to specify a library file but not a binary file as a created file.

### b. Target Install

- Command `% make install`
- Process Installs (copies) files created by `make build` to other directories.
- Procedure
  1. Execute the `make clean` command for each directory set in `SUBDIRS`.
  2. Copy files to the directory specified by `INSTALL_DIR` when there are files specified in the `INSTALL_TARGETS` variable.

You can specify the installation destination from the command line as follows:

```
% make INSTALL_DIR=/HOME/MYDIR
```

### c. Target Run

- Command `% make run`
- Process Starts execution of the target files created by `make build` when the environment allows the IS-NITRO-EMULATOR to be used.

Only 1 copy of IS-NITRO-EMULATOR may be running at any one time. If the IS-NITRO-EMULATOR is already running, an error dialog box will appear. To continue, you must end one program before executing a file.

### d. Target Full

- Command `% make full`
- Process Creates files for all versions of `make build` compiler targets.
- Procedure Execute `make build` for all compiler targets.

### e. Target Clean

- Command `% make clean`
- Process Deletes files created by `make build`.
- Procedure
  1. Execute the `make clean` command for each directory set in `SUBDIRS`.
  2. Delete temporary directories for object files and temporary directories for binary files.
  3. Delete files specified in `LDIRT_CLEAN`.

Files copied by `make install` are not deleted. Use `make clobber` to delete installed files.

**f. Target Clobber**

- Command `% make clobber`
- Process `Deletes files created by make build`
- Procedure
  1. Execute the `make clobber` command for each directory set in `SUBDIRS`.
  2. Delete temporary directories for object files and temporary directories for binary files.
  3. Delete files installed by `make build / make install`.
  4. Delete files created by `LDIRT_CLEAN` and files created by `LDIRT_CLOBBER`.

Deletes installed files in addition to the `make clean` operation.